

File Formats Used On GM

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SRF Format

- https://strike.scec.org/scecpedia/Standard_Rupture_Format
- [SRF-Description-Graves_2.0.pdf](#)
- SRF File Format Version 1 (output of genslip): [srf_description_version_1.pdf](#)
- Details on Source Modelling : [Source Modelling for GMSim](#)

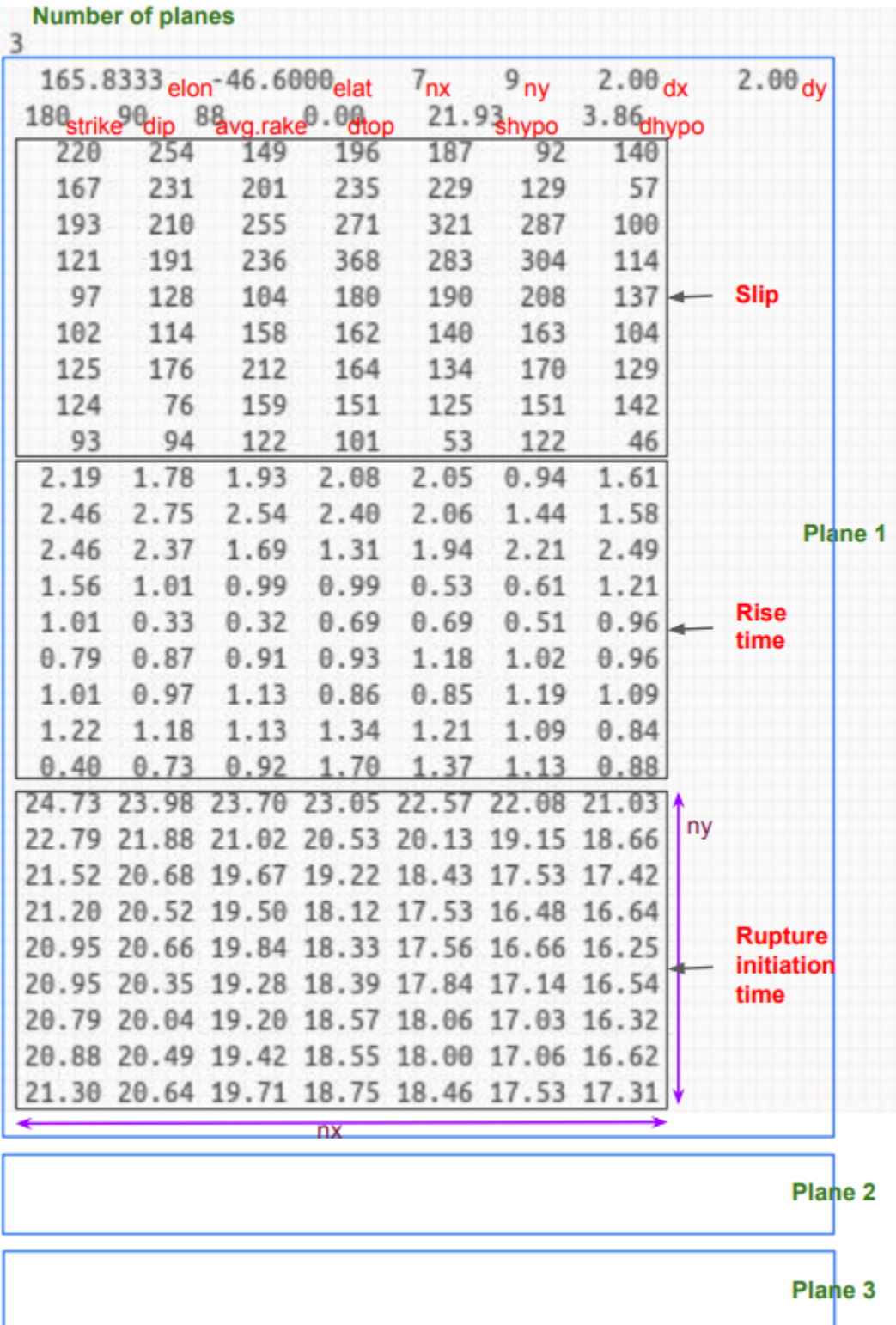
SRF info format

The **.info** files that accompany **.srf** files are in **HDF5** format

Example (CBalleny.info)

Group	
Path	/
File Path	CBalleny.info
Raw	► Inspect
Attributes	
Centre	[[165.833328,-46.599995],[165.816666,-46.708332],[165.800003,-46.941662]]
Corners	[[[165.833328,-46.533519689819904],[165.833328,-46.6664703101801],[165.833328,-46.533519689819904]], [[165.83292856835644,-46.66668097572494],[165.8003783151683,-46.749980716873175],[165.8003783151683,-46.749980716873175], [165.83292856835644,-46.66668097572494]],[[165.800003,-46.749871746980375],[165.800003,-47.13345225301961],[165.800003,-47.13345225301961], [165.800003,-46.749871746980375]]]
Dbottom	[18,18,18]
Dhyp	[3.8575,-999.9,-999.9]
Dhyp0	3.85753669909383
Dip	[90,90,90]
Dt	0.005
Dtop	[0,0,0]
Hdepth	3.85
Hlat	-47.028778
Hlon	165.800003
Length	[14.8,9.6,42.7]
Mag	7.082216870560312
Ndip	[180,180,180]
Nstrike	[148,96,427]
Rake	90
Shyp	[21.9291,-999.9,-999.9]
Shyp0	[21.92912052127512]
Strike	[180,195,180]
Tect_type	"ACTIVE_SHALLOW"
Type	4
Vm	"lp_generic1d-gp01_v1.vmod"
Width	[18,18,18]

Stoch format



LF/HF/BB binary format

These files store timeseries data. All formats follow a style derived from the LF seis format produced by EMOD3D:

1. station size, common metadata
2. station list with station metadata
3. timeseries

Numbers are 4 bytes in length and may be little or big endian. You can see or use the **existing interfaces** that also take care of endianness at [github: ucgmsim/qcore/qcore/timeseries.py](https://github.com/ucgmsim/qcore/qcore/timeseries.py)::LFSeis, HFSeis, BBSeis.

File size can be derived knowing the format and the number of stations, and shape of time-series (all necessary values are at the beginning of the file).

The **second section is repeated** for each station.

The LF format contains unnecessarily repeated common metadata in the station list section (in italics below).

In BB, **stations are ordered** to match the station input file used in the LF. This means if there was an 'index of station in input file' in BB, it would run incrementally from 0. This is also the case for HF however it is based on the station file given which should therefore be the same (same order of stations) and this is currently a requirement for BB.

HF and BB have gaps between the first 2 sections to allow future additions to section 1 without breaking backwards compatibility.

LF	HF	BB
i4 number of stations TOTAL 4 BYTES	i4 number of stations i4 number of timesteps i4 seed used in simulation i4 site amplification used (bool) i4 path duration method <ul style="list-style-type: none"> 0: GP2010 formulation 1: WUS modification trial/error 2: ENA modification trial/error 11: WUS formulation of BT2014 over predicts for multiple rays 12: ENA modification trial/error over predicts for multiple rays i4 number of ray methods known options for first-fourth type below: <ul style="list-style-type: none"> 1: direct 2: moho i4 first ray method used i4 second ray method used i4 third ray method used i4 fourth ray method used i4 nbu parameter i4 ift parameter i4 nlskip parameter i4 icflag parameter (bool) i4 individually run stations (bool) i4 site specific VMs used (bool) f4 duration of timeseries (s) f4 timestep of timeseries (s) f4 start time of timeseries (s) f4 stress drop average (bars) f4 kappa parameter f4 q frequency exponent f4 max sim frequency (Hz) f4 flo parameter (Hz) f4 fhi parameter (Hz) f4 rupture velocity factor (rupture : Vs) f4 rvfac shallow fault multiplier f4 rvfac deep fault multiplier f4 czero coefficient, -1: used binary default f4 calpha coefficient, -1: used binary default f4 seismic moment, -1: used rupture model f4 rupture velocity, -1: used rupture model f4 depth to moho, -1: used binary default (999.9) f4 vp_sig parameter sig parameters are likely uncertainties f4 vsh_sig parameter f4 rho_sig parameter f4 qs_sig parameter f4 fourier amplitude uncertainty (1) f4 fourier amplitude uncertainty (2) f4 rupture velocity uncertainty s64 stoch file used (basename) s64 velocity model used (basename) TOTAL 288 BYTES	i4 number of stations i4 number of timesteps f4 duration of timeseries (s) f4 timestep of timeseries (s) f4 start time of timeseries (s) s256 LF directory path used s256 LF VM directory path used s256 HF file path used possibly add vsite file path used here? TOTAL 788 BYTES

START OFFSET 4 BYTES i4 index of station in input file i4 x gridpoint of station i4 y gridpoint of station i4 z gridpoint of station i4 simulation number of timesteps f4 simulation timestep (s) f4 simulation grid spacing (km) f4 simulation grid rotation (degrees) f4 latitude of station (degrees) f4 longitude of station (degrees) s8 name of station TOTAL 48 BYTES * NUM_STATIONS	START OFFSET 512 BYTES f4 longitude of station (degrees) f4 latitude of station (degrees) s8 name of station f4 epicentre distance to station (km) f4 vs30 at station (m/s) TOTAL 24 BYTES * NUM_STATIONS	START OFFSET 1280 BYTES f4 longitude of station (degrees) f4 latitude of station (degrees) s8 name of station i4 x gridpoint of station i4 y gridpoint of station i4 z gridpoint of station f4 epicentre distance to station (km) f4 HF vs30ref (m/s) f4 LF vs30ref (m/s) f4 BB vs30 (m/s) TOTAL 44 BYTES * NUM_STATIONS
START OFFSET 0 FROM ABOVE f4 velocity (cm/s) timeseries in array dimensions: timestep, station, component (x, y, z, ..., 9) TOTAL 4 BYTES * PRODUCT_OF_DIMENSIONS	START OFFSET 0 FROM ABOVE f4 acceleration (cm/s^2) timeseries in array dimensions: station, timestep, component (x, y, z) TOTAL 4 BYTES * PRODUCT_OF_DIMENSIONS	START OFFSET 0 FROM ABOVE f4 acceleration (g) timeseries in array dimensions: station, timestep, component (x, y, z) TOTAL 4 BYTES * PRODUCT_OF_DIMENSIONS

XYTS.e3d binary format

This file is produced by EMOD3D and contains a timeseries of ground motions on the XY plane. Unlike the LF seis files, this contains data at all grid points and may have a decimated resolution specified when running EMOD3D through the *e3d.par* file with the parameters *dxts* and *dyts*.

Numbers are 4 bytes in length and may be little or big endian. You can see or use the **existing interfaces** that also take care of endianness at [github: ucgmsim/qcore/qcore/xyts.py::XYTSFile](#).

File size can be derived knowing the format and the shape of time-series (all necessary values are at the beginning of the file).

The **gridpoints are based on a model** which is an area with equidistant gridpoints in the X, Y, and Z directions. It is centred on a position (longitude, latitude) and may be rotated.

1. **simulation metadata**
 - a. **INTEGERS**
 - i. number of first x gridpoint
 - ii. number of first y gridpoint
 - iii. number of first z gridpoint
 - iv. number of first timestep
 - v. number of x gridpoints
 - vi. number of y gridpoints
 - vii. number of z gridpoints (always 1 by definition of X-Y file)
 - viii. number of timesteps
 - b. **FLOATS**
 - i. x spacing between given gridpoints (km)
 - ii. y spacing between given gridpoints (km)
 - iii. original (pre-decimated) grid spacing between gridpoints used in simulation (km)
 - iv. timestep in timeseries (s)
 - v. model rotation of gridpoints (degrees)
 - vi. model centre latitude (degrees)
 - vii. model centre longitude (degrees)
2. **timeseries**
 - float array of velocities in the dimensions of **timesteps, components** (x, y, z), **y** grid positions, **x** grid positions.

Intensity Measure calculation

The IM calculation code will produce a number of text files (decided as of 25/05/2018). We will summarize them in the following.

Intensity measure files

There are two types of IM files: per station and aggregate. The per station one has the following format:

```
component, IM_1, IM_2, . . . . , IM_N
```

Note: The per station file does not have the station name, as it is the file name.

The aggregate one has all the stations on a single place:

```
station, component, IM_1, IM_2, ..., IM_N
```

Empirical IMs

As above the empirical intensity measures have a similar format:

```
station, component, IM_1, IM_1_sigma, IM_2, IM_2_sigma, ..., IM_N, IM_N_sigma
```

Notes: 1) the component for empirical IMs is always 'geom' 2) only total sigma is saved to the csv file

Rrup file

The file format for this is:

```
station, lat, lon, rrup, rjbs, rx
```

Note: we don't have rx calculations yet, so we may dump an invalid value just to conform with the format.

Metadata file

So far the requirements indicate that we need:

```
identifier, rupture, type, date, version
```